# **AIE110-XNX Series**

**Edge AI Embedded System** 

**User's Manual** 



# USER'S MANUAL



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#### **CAUTION**

If you replace wrong batteries, it causes the danger of explosion. It is recommended by the manufacturer that you follow the manufacturer's instructions to only replace the same or equivalent type of battery, and dispose of used ones.

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# **ESD Precautions**

Computer boards have integrated circuits sensitive to static electricity. To prevent chipsets from electrostatic discharge damage, please take care of the following jobs with precautions:

- Do not remove boards or integrated circuits from their anti-static packaging until you are ready to install them.
- Before holding the board or integrated circuit, touch an unpainted portion of the system unit chassis for a few seconds. It discharges static electricity from your body.
- Wear a wrist-grounding strap, available from most electronic component stores, when handling boards and components.

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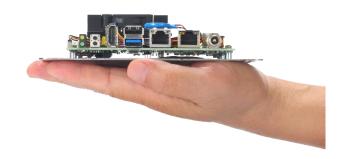
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# SECTION 1 INTRODUCTION





This chapter contains general information and detailed specifications of the AIE110-XNX. The Chapter 1 includes the following sections:

- General Description
- Developer kit Specifications
- Dimensions
- I/O Outlets
- Packing List
- Model List

# 1.1 General Description

The AIE110-XNX is a palm-sized developer kit with NVIDIA® Jetson Xavier™ NX Series supercomputer-on-a-module that delivers outstanding AI performance, excellent I/O flexibility, varied peripherals, and accommodation for board support packages (BSP).

It enables users to easily convert the developer kit to an edge system using Axiomtek industrial design services.

This developer kit is equipped with one 8 GB 128-bit LPDDR4x memory, one 16GB eMMC, and a built-in watchdog timer. It also features one GbE, one GbE PoE, one USB 3.2 Gen2, one USB 2.0, one HDMI2.0, and one mini PCI-Express slot with USB and PCIe signal. Additionally, it offers users one M.2 Key M NVMe slot and one Micro SD slot that provides extra storage options for makers to process the massive data and the edge AI application development.

There are more interfaces available, such as 8CH DIO, debug port, recovery switch, Micro USB for image flash, and more.

#### Features

- 1. NVIDIA® Jetson Xavier™ NX with Volta™, 384 CUDA cores GPU
- 2. 1 USB 2.0, 1 USB 3.2 Gen2, 1 GbE and 1 GbE PoE (15W)
- 3. 1 M.2 Key M NVMe SSD slot and 1 Micro SD slot for extra storage
- 4. 1 Mini PCI-Express slot & SIM slot for Wi-Fi / Bluetooth / LTE / GPS
- 5. 12VDC Power input (DC Jack Screw Type)

### JetPack Supported

The AIE110-XNX supports JetPack 4.6.2 or later. NVIDIA JetPack SDK is the most comprehensive solution for building AI applications.

JetPack supports Jetson AGX Xavier<sup>TM</sup>, Jetson Xavier<sup>TM</sup> NX, Jetson<sup>TM</sup> TX2 NX, Jetson<sup>TM</sup> Nano and Jetson TX2 series. It bundles all the Jetson platform software, including TensorRT, cuDNN, CUDA Toolkit, VisionWorks, GStreamer, and OpenCV, all built on top of L4T with LTS Linux kernel.

#### OS Supported

The AIE110-XNX supports Linux Ubuntu 18.04 or later.

#### Various Storage devices supported

For storage device, the AIE110-XNX supports one M.2 2280 Key M with PCI-Express 2.0 x4 interface, an onboard 16GB eMMC 5.1 and one Micro SD interface.

# 1.2 Developer Kit Specifications

#### 1.2.1 Product Specification

- NVIDIA Jetson SoM
  - NVIDIA® Jetson Xavier<sup>TM</sup> NX Series
- CPU
  - 6-core NVIDIA Carmel ARM®v8.2 64-bit CPU 6 MB L2 + 4 MB L3
- GPU
  - 384-core NVIDIA Volta<sup>™</sup> GPU with 48 Tensor Cores
- Storage
  - 16GB eMMC 5.1 onboard
  - One M.2 2280 M Key with PCI-Express 2.0 x4 NVMe SSD slot
  - One Micro SD slot to support optional Micro SD card (UHS-I compatible)
- System Memory
  - One 8 GB 128-bit LPDDR4x onboard
- WLAN & WWAN
  - One PCI Express Mini Card modules slot to support Wi-Fi or 3G/4G/LTE modules

#### 1.2.2 I/O System

- One HDMI 2.0 for display (HDMI 2.0 Resolution: up to 4096 x 2160@60Hz)
- One RJ-45 connector for 10/100/1000 Base-T Ethernet port
- One RJ-45 connector for 10/100/1000 Base-T PoE (IEEE 802.3af; PSE), max. up to 15.4 Watts



<u>Note</u>: AIE110 is a power supply device. Two PSE devices should not be connected together, which may cause the risk of power conflict. Correctly connect PD Device or switch without PoE. If you need PoE switch, please find the switch with uplink port.

- One USB 2.0 and one USB 3.2 Gen2 connectors
- Front-access design for ease of updating NVIDIA Jetpack
  - One Micro USB connector for image flash only
  - One Recovery switch
- One Micro SD slot for extra storage (UHS-I compatible)
- One M.2 2280 Key M with PCI-Express 2.0 x4 SSD slot for extra storage
- One full-size PCI Express Mini Card slot (USB + PCI Express signal)
- One Power button and one Reset button
- Two LED Indicators (System Power, M.2 Storage)
- One 12 VDC Power Jack connector

# 1.2.3 System Specification

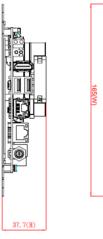
- Watchdog Timer
  - Built-in NVIDIA® Jetson Xavier<sup>TM</sup> NX Series
- Power Supply
  - Input: 12 VDC
- Thermal Solution
  - Active heatsink
- Operation Temperature
  - -10°C ~ +60°C (-14°F ~ +140°F)
- Humidity
  - 10% ~ 95% (non-condensing)
- Weight
  - 0.3 kg (0.66 lb) without package
  - 0.9 kg (1.98 lb) with package
- Dimensions
  - 165 mm (6.49") (W) x 117 mm (4.60") (D) x 37.7 mm (1.48") (H)
- Note: All specifications and images are subject to change without notice.

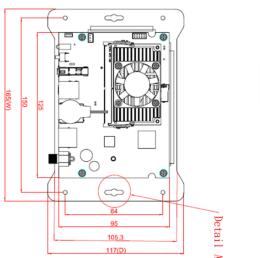
# 1.3 Dimensions

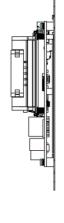
The following diagrams show the dimensions and outlines of the AIE110-XNX.

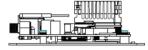
# 1.3.1 Developer Kit Dimensions

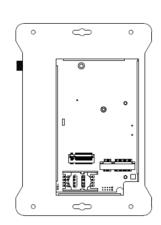


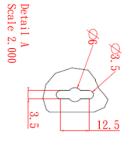




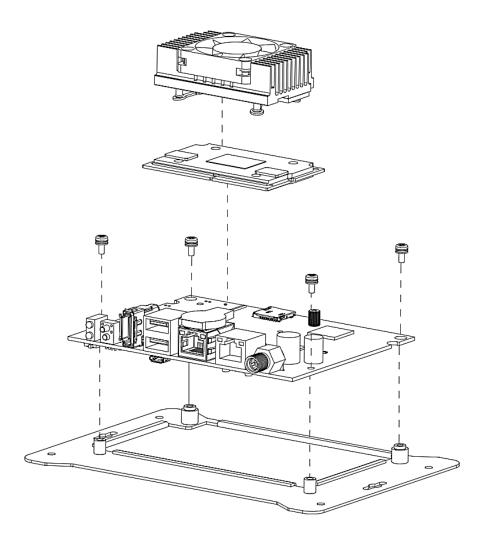








# 1.3.2 Assembly Drawing



# 1.4 Packing List

The package bundled with your AIE110-XNX should contain the following items:

- AIE110-XNX Developer Kit Unit x 1
- Digital I/O Cable x 1
- (Optional) Power Adapter
- (Optional) Power Cord
- (Optional) M.2 Key M NVMe SSD
- (Optional) Wi-Fi or LTE module kit

\*Regarding the latest product manual, please download them from Axiomtek official website.

## 1.5 Model List

	lge AI Developer Kit with NVIDIA® Jetson Xavier™ NX SoM, 1 DMI, 1 GbE LAN, 1 GbE PoE and 2 USB
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If you cannot find this package or any items are missing, please contact Axiomtek distributors immediately.

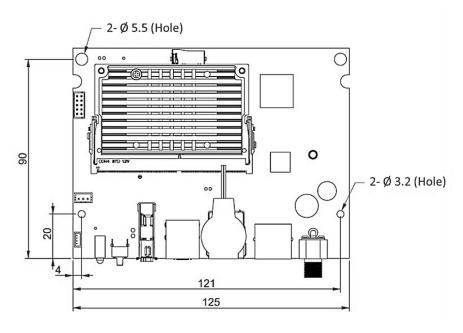
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# SECTION 2 BOARD AND PIN ASSIGNMENTS

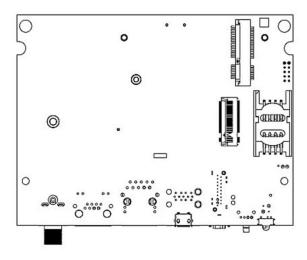
Proper jumper settings configure the **AIE110-XNX** to meet your application purpose. We are here with listing a summary table of all jumpers and default settings for onboard devices, respectively.

# 2.1 Board Dimensions and Fixing Holes

#### **Top View**

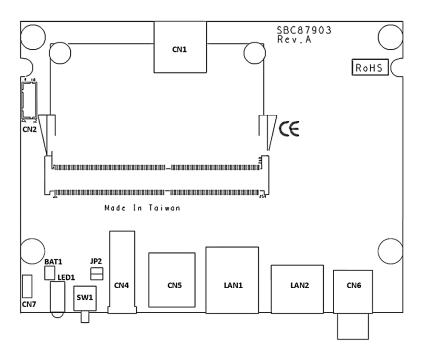


#### **Bottom View**

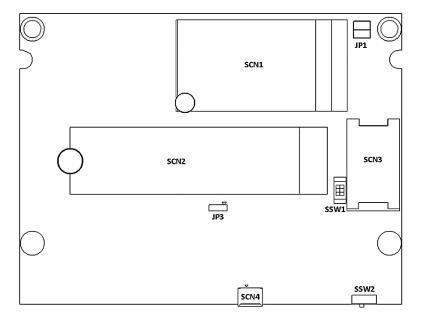


# 2.2 Board Layout

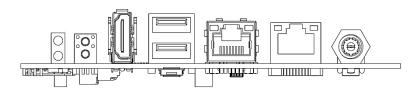
**Top View** 



#### **Bottom View**



#### Side View



# ♦ Note:

We strongly recommended that you should not modify any unmentioned jumper setting without Axiomtek FAE's instruction. Any modification without instruction might cause damage to the system.

# 2.3 Connectors and Switches

Connectors connect the board with other parts of the system. Loose or improper connection might cause problems. Make sure all connectors are properly and firmly connected. Here is a summary table shows you all connectors and button on the **AIE110-XNX** Series.

External Connectors / Buttons	PCB Location	Section
MicroSD slot	CN1	2.3.1
Digital I/O Connector	CN2	2.3.2
HDMI Connector	CN4	2.3.3
USB2.0 & USB3.1 Gen2 Connector	CN5	2.3.4
DC-in Connector	CN6	2.3.5
5V Fan Connector	CN7	2.3.6
PCI-Express Mini Card slot	SCN1	2.3.7
M.2 2280 Key M PCIe x4 SSD slot	SCN2	2.3.8
SIM Card Slot	SCN3	2.3.9
Micro USB 2.0 Connector (For Jetpack flash)	SCN4	2.3.10
Ethernet Ports	LAN1	2.3.11
PoE Ports	LAN2	2.3.11
Power Button & Reset Button	SW1	2.3.12
AT/ATX Switch	SSW1	2.3.13
Recovery Mode Switch (For Jetpack flash)	SSW2	2.3.14
Debug Port Connector	JP1	2.3.15
Reserved Connector:  Power Button & Recovery mode	JP2	2.3.16
I <sup>2</sup> C Connector	JP3	2.3.17
CMOS Battery Interface	BAT1	2.3.18
Power and Storage LED Indicator	LED1	2.3.19

# 2.3.1 Micro SD Slot (CN1)

The Micro Secure Digital (SD) is a flash memory card format used in portable device including notebook and digital camera.

Pin	in Signal Pi		Signal
1	DATA1	5	+3.3VS
2	DATA0	6	CMD
3	GND	7	DATA3
4	CLK	8	DATA2

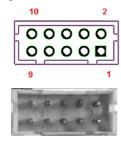


# 2.3.2 Digital I/O Header (CN2)

The CN12 is a 2 x 5-pin header for 8-Channel digital I/O interface.

The digital I/O is controlled via software programming.

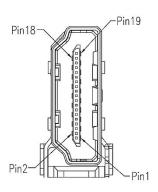
Pin	Signal	Pin	Signal
1	DIO1	2	DIO2
3	DIO3	4	DIO4
5	DIO5	6	DIO6
7	DIO7	8	DIO8
9	+5V_SBY	10	GND



# 2.3.3 HDMI Connector (CN4)

The HDMI (High-Definition Multimedia Interface) is a compact digital interface which is capable of transmitting high-definition video and high-resolution audio over a single cable.

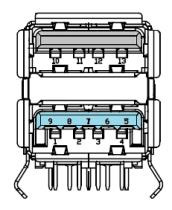
Pin	Signal	Pin	Signal
1	HDMI1_DATA2+	2	GND
3	HDMI1_DATA2-	4	HDMI1_DATA1+
5	GND	6	HDMI1_DATA1-
7	HDMI1_DATA0+	8	GND
9	HDMI1_DATA0-	10	HDMI1_CLK+
11	GND	12	HDMI1_CLK-
13	HDMI_CEC	14	NC
15	HDMI1_SCL	16	HDMI1_SDA
17	GND	18	+5V
19	HDMI_HTPLG		



# 2.3.4 USB2.0 & USB3.1 Gen2 Connector (CN5)

The Universal Serial Bus connectors are compliant with USB 2.0 (480Mbps) and USB 3.1 Gen2 (10Gbps), and ideally for installing USB peripherals such as keyboard, mouse, scanner, etc.

Pin	Signal	Pin	Signal		
1	5V_USB1	7	GND		
2	USB1_D-	8	USB_SS1_TX-		
3	USB1_D+	9	USB_SS1_TX+		
4	GND	10	5V_USB2		
5	USB_SS1_RX-	11	USB2_D-		
6	USB_SS1_RX+	12	USB2_D+		
13	GND				



# 2.3.5 DC Power Jack w/ Screw (CN6)

The CN6 is a DC jack with screw. Firmly insert at least 60W adapter into this connector. Loose connection may cause system instability and make sure all components/devices are properly installed before connecting.

Pin	Signal
1	12V
2	GND

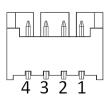




# 2.3.6 5V Fan Connector (CN7)

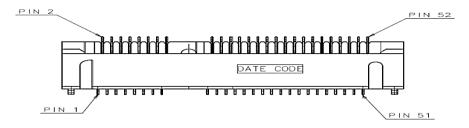
This is a 4-pin connector for smart fan interface.

Pin	Signal
1	GND
2	+5V
3	TACH
4	PWM (5V)



# 2.3.7 PCI-Express Mini Card Connector (SCN1)

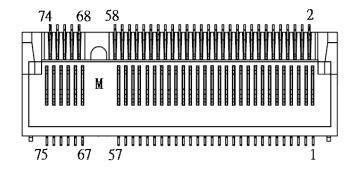
The AIE110-XNX supports a full-size PCI-Express Mini Card slots. SCN1 is applying to either PCI-Express or USB 2.0 signal, and complies with PCI-Express Mini Card Spec. V1.2.



Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal
1	WAKE#	2	+3.3V	3	NC	4	GND
5	NC	6	+1.5V	7	CLKREQ#	8	UIM_PWR
9	GND	10	UIM_DATA	11	REFCLK-	12	UIM_CLK
13	REFCLK+	14	UIM_RESET	15	GND	16	UIM_VPP
17	NC	18	GND	19	NC	20	WLAN_DISABLE# / Xavier™ NX's GPIO05
21	GND	22	NC	23	PEX2_RX-	24	+3.3V
25	PEX2_RX+	26	GND	27	GND	28	+1.5V
29	GND	30	Xavier™ NX's I2C2_SCL	31	PEX2_TX-	32	Xavier™ NX's I2C2_SDA
33	PEX2_TX+	34	GND	35	GND	36	USB2.0_D-
37	GND	38	USB2.0_D+	39	+3.3V	40	GND
41	+3.3V	42	LED_WWAN#	43	GND	44	NC
45	NC	46	NC	47	NC	48	+1.5V
49	NC	50	GND	51	NC	52	+3.3V

# 2.3.8 M.2 2280 Key M PCle x4 SSD slot (SCN2)

The AIE110-XNX comes with one M.2 2280 Key M PCIe x4 NVMe SSD slot for storage.

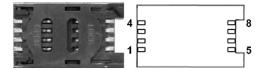


Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal
1	GND	2	+3.3V	3	GND	4	+3.3V
5	PEX3_RX-	6	NC	7	PEX3_RX+	8	NC
9	GND	10	LED_1#	11	PEX3_TX-	12	+3.3V
13	PEX3_TX+	14	+3.3V	15	GND	16	+3.3V
17	PEX2_RX-	18	+3.3V	19	PEX2_RX+	20	NC
21	GND	22	NC	23	PEX2_TX-	24	NC
25	PEX2_TX+	26	NC	27	GND	28	NC
29	PEX1_RX-	30	NC	31	PEX1_RX+	32	NC
33	GND	34	NC	35	PEX1_TX-	36	NC
37	PEX1_TX+	38	M.2_DEVSLP	39	GND	40	NC
41	PEX0_RX-	42	NC	43	PEX0_RX+	44	NC
45	GND	46	NC	47	PEX0_TX-	48	NC
49	PEX0_TX+	50	PERST#	51	GND	52	CLKREQ#
53	PEX0_REFCLKn	54	PEWAKE#	55	PEX0_REFCLKp	56	NC
57	OND	58	NO	59	CONNECTOR	60	CONNECTOR
01	GND	00	NC	00	Key M	00	Key M
61	CONNECTOR	62	CONNECTOR	63	CONNECTOR	64	CONNECTOR
	Key M	02	Key M		Key M	•	Key M
65	CONNECTOR Key M	66	CONNECTOR Key M	67	NC	68	NC
69	NC	70	+3.3V	71	GND	72	+3.3V
73	GND	74	+3.3V	75	GND		

# 2.3.9 SIM Card Slot (SCN3)

AIE110-XNX comes with SIM Card Slot (SCN3) for inserting SIM Card. In order to work properly, the SIM Card must be used together with 3G/LTE module which would be inserted to PCI-Express Mini Card Connector (SCN1). It is mainly used for 3G/LTE wireless network application.

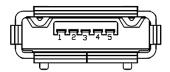
Pin	Signal	Pin	Signal
1	UIM PWR	5	GND
2	UIM RST	6	UIM VPP
3	UIM CLK	7	UIM DATA
4	NC	8	NC



# 2.3.10 Micro USB 2.0 Connector (SCN4)

The SCN4 is specifically designed for image flashing only. To flash Jetpack, please switch SSW2 to ON before booting up the system, which would force the system to recovery mode.

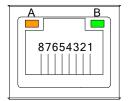
Pin	Signal
1	+5V
2	USB0 DN
3	USB0 DP
4	GND
5	GND



# 2.3.11 Ethernet Ports (LAN1, LAN2)

The AIE110-XNX comes with two RJ-45 connectors: LAN1 (NVIDIA® Jetson Xavier™ NX) and LAN2 (Intel® I210-IT). LAN1 is a GbE port, but LAN2 is the GbE PoE port (non-isolated), which is compliant IEEE 802.3af class 3, and the total power budget is 15Watts maximum.

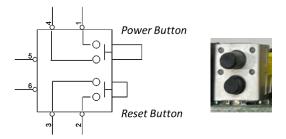
	LAN1	LAN2 (PoE)		
Pin	Signal	Pin	Signal	
1	Tx+(Data transmission positive)	1	Tx+ (Data transmission positive)	
2	Tx-(Data transmission negative)	2	Tx- (Data transmission negative)	
3	Rx+(Data reception positive)	3	Rx+(Data reception positive)	
4	RJ-1(For 1000 base T-Only)	4	RJ-1(For 1000 base T- Only)	
5	RJ-1(For 1000 base T-Only)	5	RJ-1(For 1000 base T- Only)	
6	Rx- (Data reception negative)	6	Rx- (Data reception negative)	
7	RJ-1(For 1000 base T-Only)	7	RJ-1(For 1000 base T- Only)	
8	RJ-1(For 1000 base T-Only)	8	RJ-1(For 1000 base T- Only)	
Α	Active LED	Α	Active LED	
В	Speed LED (1000M)	В	Speed LED (1000M / 100M)	



# 2.3.12 Power Button & Reset Button (SW1)

Power button can allow users to either turn on the AIE110-XNX or forcibly shut down the system, and the reset button can allow users to reset AIE110-XNX during system abnormal situation.

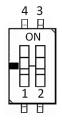
Pin	Signal	
1	GND	
2	GND	
3	RST_BTN	
4	PWR_BTN	
5	GND	
6	GND	



# 2.3.13 AT/ATX Switch (SSW1)

If you turn OFF the Pin1 (AT mode) of SSW1, the system will be automatically power on without pressing soft power button during power input; we can use this switch to achieve auto power on demand.

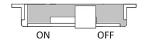
Pin	Description	ON (Default)	OFF
1	AT / ATX Mode	ATX	AT
2	NC	NC	NC



# 2.3.14 Recovery Mode Switch (SSW2)

It will make NVIDIA® Jetson Xavier™ NX force recovery mode when switching SSW2 to ON before booting up the system.

Pin	Signal	
ON	Recovery Mode	
OFF	Normal	



# 2.3.15 Debug Port Header (JP1)

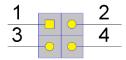
The JP1 is the serial debug port (UART Port0) for debugging purposes at software development.

Pin	Signal	
1	+5V	
2	UART2_TXD_3.3V	
3	GND	
4	UART2_RXD_3.3V	

# 2.3.16 Reserved Connector: Power Button & Recovery mode (JP2)

JP2 is a reserved connector for entering recovery mode (1-2) and power button (3-4). It supports the same function as SSW2 and SSW1(Power button only).

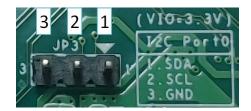
Pin	Signal
1	Recovery_N
2	GND
3	PWR_BTN
4	GND



# 2.3.17 I<sup>2</sup>C Connector (JP3)

JP3 is connect to I²C port 0 of the NVIDIA® Jetson Xavier™ NX, and it has pull up 2.2k ohm to 3.3V on carrier board.

Pin	Signal	
1	I <sup>2</sup> C0_SDA (3.3V)	
2	I <sup>2</sup> C0_SCL (3.3V)	
4	GND	



# 2.3.18 CMOS Battery Interface (BAT1)

This connector is for CMOS battery interface.

Pin	Signal
1	+VBAT
2	GND



# 2.3.19 Power and Storage LED Indicator (LED1)

The Yellow LED is linked to Solid-state Drive (SSD) activity signal. LED flashes every time SSD is accessed. The power LED (Green) lights up and will remain steady while the system is powered on.

LED Color	Description	
Yellow	Solid-state drive activity	
Green	Power on/off	

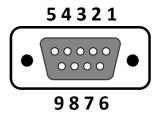


# 2.4 Cables

# 2.4.1 Digital I/O Cable

This cable is for 8-Channel digital I/O programming, please connect the digital I/O cable to Digital I/O Header (CN2).

Pin	Signal	Pin	Signal
1	DIO1	6	DIO6
2	DIO3	7	DIO4
3	DIO5	8	DIO2
4	DIO7	9	GND
5	DIO8		





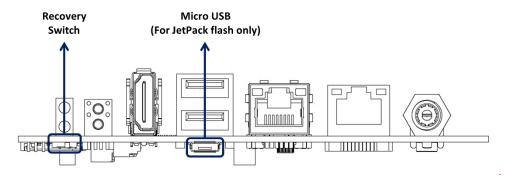
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# **SECTION 3** JETPACK BSP FLASH METHOD

This chapter provides users with a detailed description of how to flash NVIDIA Jetpack BSP for AIE110-XNX, the user could follow the below instruction to install or reinstall Jetpack BSP by themselves.

#### 3.1 JETPACK FLASH METHOD

Please use the following instructions to flash the JetPack to the AIE110-XNX.



Please contact our sales or FAE for the latest Jetpack SDK, and prepare a Linux host system running x86\_64 Ubuntu v16.04

Note: If the Linux host system is running x86\_64 Ubuntu v18.04, please follow the instructions below to install Python first.

> Step 1. Connect the Linux host system to internet Step 2. Install Python with the command below:

sudo apt-get update sudo apt-get install python

- 1. AIE110-XNX connection as follows:
  - Connect a USB cable from the Linux host system to the Micro USB port at AIE110-XNX, and switch the recovery switch to ON. For more details, please refer to 2.4.13 Recovery Mode Switch (SSW2).
  - Connect an HDMI monitor to AIE110-XNX.
- 2. Open the terminal at the host system, and change the path to the image file directory, e.g., "~/Downloads", and check image tarball data integrity with the following commands:
- cd ~/Downloads
- md5sum -c <image tarball file name>.tbz2.md5sum

#### For example:

\$ md5sum -c mfi\_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0.tbz2.md5sum axio@axio-B460MD3H: ~/Downloads

axio@axio-B460MD3H:~/Downloads\$ md5sum -c mfi\_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0.tbz2.md5sum mfi\_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0.tbz2: OK axio@axio-B460MD3H:~/Downloads\$

3. If the check result returns OK, untar the image file with the command below:

```
$ tar jxvf <image_tarball_file_name>.tbz2
```

#### For example:

\$ tar jxvf mfi\_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0.tbz2

```
axio@axio-B460MD3H: ~/Downloads
```

```
axio@axio-B460MD3H:~/Downloads$ tar jxvf mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0.tbz2
```

4. Change the directory to the image package folder with the command below:

```
$ cd <image file name>
```

#### For example:

```
$ cd mfi jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0
```

```
axio@axio-B460MD3H: ~/Downloads/mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0
```

```
axio@axio-B460MD3H:~/Downloads$ cd mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0
axio@axio-B460MD3H:~/Downloads/mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0$
```

5. Make sure the recovery switch(SSW2) has been switched to ON, and run the command Isusb, then the command line "0955:7e19 Nvidia Corp." should be listed.

#### \$ lsusb

🗬 axio@axio-B460MD3H: ~/Downloads/mfi\_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0

```
axio@axio-B460MD3H:~/Downloads/mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0$ lsusb Bus 002 Device 001: ID ld6b:0003 Linux Foundation 3.0 root hub Bus 001 Device 071: ID lc4f:0002 SiGma Micro Keyboard TRACER Gamma Ivory Bus 001 Device 105: ID 0955:7e19 NVidia Corp.
Bus 001 Device 005: ID 05e3:0608 Genesys Logic, Inc. Hub Bus 001 Device 004: ID lc4f:0034 SiGma Micro
Bus 001 Device 001: ID ld6b:0002 Linux Foundation 2.0 root hub axio@axio-B460MD3H:~/Downloads/mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0$
```

6. Running the following command to flash the image.

```
$ sudo ./nvmflash.sh

axio@axio-B460MD3H: ~/Downloads/mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0

axio@axio-B460MD3H: ~/Downloads/mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0$ sudo ./nvmflash.sh

Start flashing device: 1-7, PID: 19855

Ongoing processes: 19855
```

7. The flashing procedure takes approximately 20 minutes or more. Once finished, you should see "Flash complete (SUCCESS)" as shown below, and AIE110-XNX will automatically reboot, and please switch the recovery switch(SSW2) to OFF to return to standard mode.

```
Ongoing processes: 19855
Ongoing processes:
Flash complete (SUCCESS)
axio@axio-B460MD3H:~/Downloads/mfi_jetson-xavier-nx-JP4.6.2-SBC87903-V1.0.0$
```

#### THE DEFAULT LOGIN CREDENTIALS:

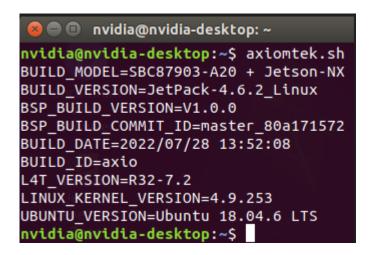
Username: nvidia Password: nvidia

#### **\*CAUTION:**

Running \$ sudo apt upgrade command for NVIDIA JetPack OTA may overwrite the BSP of the AIE series platform, which can cause unexpected results including losing I/O ports. For regular JetPack updates or reflashing, please contact our sales or FAE to get the latest AIE Series JetPack image.

# 3.2 Image Information Inquiry Command

Running axiomtek.sh command to inquiry the current image information, image version, L4T version, Linux kernel version, and Ubuntu version.



# 3.3 JTOP-Third-party Jetson Platform Monitor Tool

JTOP is a third-party system monitoring utility that runs on the terminal to see and control realtime the status of the AIE Series Platform. CPU, RAM, GPU status, power mode management, toolkits version and more.

#### Installation Guide:

Please connect to the internet and enter the following commands in the terminal to install JTOP.

```
$ sudo apt install python-pip python3-pip
$ sudo pip3 install -U jetson-stats
```

Once installation is completed, reboot the device and then type the below command in the terminal to launch JTOP:

```
$ sudo jtop
```

Note: JTOP may require approximately 200 to 300 MB of storage space.

```
🗎 📵 jtop Xavier NX (Developer Kit Version) - JC: Inactive - 20W 6CORE
NVIDIA Jetson Xavier NX (Developer Kit Version) - Jetpack 4.6.2 [L4T 32.7.2]
               Schedutil - 22%] 1.4GHz CPU4 [||||
Schedutil - 21%] 1.4GHz CPU5 [||||
Schedutil - 17%] 1.3GHz CPU6 [||
                                                          Schedutil - 19%] 1.3GHz
Schedutil - 16%] 1.3GHz
Schedutil - 10%] 1.4GHz
PU1 [|||||
PU2 [||||
PU3 [ | | |
                                         0%] BG [
lem [|||||||||||
                                                          1.8G/8.0GB] (lfb 1353x4MB)
                                                           0.0GB/3.9GB] (cached 0MB)
   3%] 1.6GHz
                                                                            0%] 114MHz
10.9GB/13.7GB]
                                 [Sensor] -
          [info]
                                            [Temp]
                                                         [Power/mW]
                                                                       [Cur] [Avr]
UpT: 0 days 0:1:12
                                                         CPU GPU CV
                                                                       856
                                                                               1085
                  0%] Ta= 0%
   N [
                                                         SOC
                                                                       1261
                                                                               1274
                                 AHX
 Jetson Clocks: inactive
                                 CPU
                                                                       4606
                                                         ALL
                                                                               4834
NV Power[8]: 20W 6CORE
                                 GPII
                                 thermal
                                              48.90C
       [HW engines]
APE: 150MHz
NVENC: [OFF]
                NVDEC: [OFF]
NVJPG: [OFF]
1ALL 2GPU 3CPU 4MEM 5CTRL 6INFO Quit
                                                                      Raffaello Bonghi
```

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# APPENDIX A WATCHDOG TIMER

#### **About Watchdog Timer**

Software stability is major issue in most applications. Some embedded systems are not watched by human for 24 hours. It is usually too slow to wait for someone to reboot when computer hangs. The systems need to be able to reset automatically when things go wrong. The watchdog timer gives us solutions in this regard.

The watchdog timer is a counter that triggers a system to reset when it counts down to zero from a preset value. The software starts the counter with an initial value and must reset it periodically. If the counter ever reaches zero, it means the software has crashed, the system will reboot.

# A.1 Sample Program

- 1. Put "wdt.c" and "watchdog.h" two files into target AIE device.
- 2. Compile by below command line:

# gcc wdt.c -o wdt

3. Test: (default: 60 seconds, if there is no timeout value as input parameter)
# sudo ./wdt <timeout in seconds>

⇒ System will reboot automatically after timeout

```
nvidia@nvidia-desktop:~/Downloads$ cd watchdog_example_code/
nvidia@nvidia-desktop:~/Downloads/watchdog_example_code$ gcc wdt.c -o wdt
nvidia@nvidia-desktop:~/Downloads/watchdog_example_code$ sudo ./wdt
[sudo] password for nvidia:
Watchdog timeout value: 120
New watchdog timeout value: 60
nvidia@nvidia-desktop:~/Downloads/watchdog_example_code$
```

```
nvidia@nvidia-desktop:~/Downloads/watchdog_example_code$ sudo ./wdt 240
[sudo] password for nvidia:
Watchdog timeout value: 120
New watchdog timeout value: 240
nvidia@nvidia-desktop:~/Downloads/watchdog_example_code$
```

### A.2 wdt.c

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <fcntl.h>
#include <errno.h>
#include <sys/ioctl.h>
#include <sys/types.h>
int main(int argc, char **argv)
  int fd, ret;
 int timeout = 0;
  fd = open("/dev/watchdog0", O RDWR);
  if (fd<0) {
   fprintf(stderr, "Open watchdog device failed!\n");
    return -1;
  ret = ioctl(fd, WDIOC GETTIMEOUT, &timeout);
  if(ret) {
    fprintf(stderr, "Get watchdog timeout value failed!\n");
    return -1;
  fprintf(stdout, "Watchdog timeout value: %d\n", timeout);
  if(argc > 1){
   timeout = atoi(argv[1]);
  } else {
    timeout = 60;
  ret = ioctl(fd, WDIOC_SETTIMEOUT, &timeout);
  if(ret) {
    fprintf(stderr, "Set watchdog timeout value failed!\n");
    return -1;
  fprintf(stdout, "New watchdog timeout value: %d\n", timeout);
  ret = ioctl(fd, WDIOC_KEEPALIVE, NULL);
    fprintf(stderr, "Kick watchdog failed!\n");
    return -1;
```

```
/* close WDT0 device */
close(fd);
if (ret<0) {
  fprintf(stderr, "Failed to close watchdog device.");
  return -1;
}
return 0;
}</pre>
```

# A.3 watchdog.h

```
#include <linux/ioctl.h>
#include <linux/types.h>
/*
   Generic watchdog defines. Derived from...
 * Berkshire PC Watchdog Defines
 * by Ken Hollis
#ifndef _LINUX_WATCHDOG_H
#define _LINUX_WATCHDOG_H
#define WATCHDOG IOCTL BASE 'W'
struct watchdog_info {
    __u32 options;
     _u32 firmware_version; /* Firmware version of the card */
     _u8 identity[32]; /* Identity of the board */
};
#define WDIOC GETSUPPORT
                              IOR(WATCHDOG IOCTL BASE, 0, struct
#define WDIOC_GETSTATUS
                              _IOR(WATCHDOG_IOCTL_BASE, 1, int)
                             __IOR(WATCHDOG_IOCTL_BASE, 4, int)
                             __IOR(WATCHDOG_IOCTL_BASE, 5, int)
#define WDIOC_SETTIMEOUT __IOWR(WATCHDOG_IOCTL_BASE, 6, int)
#define WDIOC_GETTIMEOUT __IOR(WATCHDOG_IOCTL_BASE, 6, int)
#define WDIOC_GETTIMEOUT __IOR(WATCHDOG_IOCTL_BASE, 6, int)
#define WDIOC KEEPALIVE
#define WDIOC SETPRETIMEOUT IOWR(WATCHDOG IOCTL BASE, 8, int)
#define WDIOC_GETPRETIMEOUT _IOR(WATCHDOG_IOCTL_BASE, 9, int)
#define WDIOC_GETTIMELEFT _IOR(WATCHDOG_IOCTL_BASE, 10, int)
#define WDIOF UNKNOWN
                           -1 /* Unknown flag error */
#define WDIOS UNKNOWN
                              -1 /* Unknown status error */
#define WDIOF OVERHEAT
                              0x0001 /* Reset due to CPU overheat */
#define WDIOF_FANFAULT
                              0x0002 /* Fan failed */
                              0x0004 /* External relay 1 */
#define WDIOF_EXTERN1
```

```
#define WDIOF_EXTERN2
                             0x0008 /* External relay 2 */
                             0x0010 /* Power bad/power fault */
#define WDIOF POWERUNDER
#define WDIOF_CARDRESET
#define WDIOF_POWEROVER
                             0x0020 /* Card previously reset the CPU */
                             0x0040 /* Power over voltage */
#define WDIOF_SETTIMEOUT
                             0x0080 /* Set timeout (in seconds) */
0x0100 /* Supports magic close char */
#define WDIOF MAGICCLOSE
                          0x0200
#define WDIOF PRETIMEOUT
                                     /* Pretimeout (in seconds), get/set */
#define WDIOF KEEPALIVEPING 0x8000
                                     /* Keep alive ping reply */
                             0x0001 /* Turn off the watchdog timer */
#define WDIOS_DISABLECARD
                             0x0002 /* Turn on the watchdog timer */
#define WDIOS ENABLECARD
#define WDIOS_TEMPPANIC
                             0x0004 /* Kernel panic on temperature trip */
#endif /* ifndef _LINUX_WATCHDOG_H */
```

# APPENDIX B PROGRAMMABLE DIGITAL I/O

## **About Programmable Digital I/O**

The AIE110-XNX supports 8 channels programmable digital I/O which allows user to program the DI or DO. For more details, please refer to the below sample code.

# **B.1** Default Setting & Command Format

#### THE DEFAULT SETTING:

DIO1 ~ 8 are all INPUT



The DIO protocol will reset to the default setting after a cold boot.

#### **COMMAND FORMAT:**

```
# i2cset -f -y <i2c_num> <device_addr> <reg_addr> <value>
# i2cget -f -y <i2c_num> <device_addr> <reg_addr>
```

#### [For Example]

# **B.2** Sample Program

#### 1. DIO Output Sample Code

## 2. DIO Input Sample Code

# **B.3** Register Table

#### Register 0 - Input Port Register Bit Description

Bit	Symbol	Access	Value	Description
7	17	read only	Х	Determined by externally applied logic level
6	16	read only	X	logic level
5	15	read only	X	
4	14	read only	Х	
3	13	read only	X	
2	12	read only	X	
1	I1	read only	Х	
0	10	read only	Х	

#### Register 1 - Output Port Register Bit Description

This register reflects the outgoing logic levels of the pins defined as outputs by Register 3. Bit values in this register have no effect on pins defined as inputs. Reads from this register return the value that is in the flip-flop controlling the output selection, **not** the actual pin value.

Legend: \* default value

Bit	Symbol	Access	Value	Description
7	07	R	1*	Reflects outgoing logic levels of pins defined as outputs by Register 3
6	O6	R	1*	defined as outputs by Register 3
5	O5	R	1*	
4	04	R	1*	
3	О3	R	1*	
2	O2	R	1*	
1	01	R	1*	
0	00	R	1*	

### Register 3 - Configuration Register Bit Description

This register configures the directions of the I/O pins. If a bit in this register is set, the corresponding port pin is enabled as an input with high-impedance output driver. If a bit in this register is cleared, the corresponding port pin is enabled as an output. At reset, the I/Os are configured as inputs with a weak pull-up to  $V_{DD}$ .

Legend: \* default value

Bit	Symbol	Access	Value	Description
7	C7	R/W	1*	1* 0 = corresponding port pin enabled as an output 1 = corresponding port pin configured as input (default value)  1* 1* 1*
6	C6	R/W	1*	
5	C5	R/W	1*	
4	C4	R/W	1*	
3	C3	R/W	1*	
2	C2	R/W	1*	
1	C1	R/W	1*	
0	C0	R/W	1*	